

Intrinsic Open-Q™ 2100 (APQ8009W) Development Kit Technical Note 22: SOM Carrier Board Design Guide

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IDENTIFICATION

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1. INTRODUCTION

1.1 Purpose

The purpose of this document is to provide guidelines and technical information for any user desiring to design their own Carrier Board for the Intrinsyc Open-Q 2100 System On Module (SOM).

For background information on the kit, please refer to <https://www.intrinsyc.com/snapdragon-embedded-development-kits/open-q-2100-development-kit/>

1.2 Scope

This document presents guidelines and technical information for designing a user specific Carrier Board for the 2100 SOM.

1.3 Intended Audience

This document is intended for end users who have purchased an Intrinsyc Open-Q 2100 (APQ8009W) Development Kit and wish to design their own custom Carrier Board for the SOM.

1.4 Organization

This document is organized as follows:

- **Section 1. Introduction:** This section describes the purpose, scope, and structure of this document.
- **Section 2. Documents:** This section lists other documents that are parents of or supplement this document.
- **Section 3. Mechanical Design Guidelines:** This section identifies the mechanical design guidelines for developing a custom Carrier Board for the Open-Q 2100 (APQ8009W) Development Kit SOM.
- **Section 4. Electrical Design Guidelines:** This section identifies the electrical design guidelines for developing a custom Carrier Board for the Open-Q 2100 (APQ8009W) Development Kit SOM.
- **Section 5. Electrical Specifications:** This section contains the electrical specifications for the Open-Q 2100 SOM.

2. DOCUMENTS

This section lists any parent and supplementary documents for the Open-Q 2100 (APQ8009W) Development Kit Technical Note. Unless stated otherwise, applicable documents supersede this document and reference documents provide background and supplementary information.

2.1 Applicable Documents

| REFERENCE | AUTHOR | TITLE |
|-----------|-----------|--|
| A-1 | Intrinsyc | Intrinsyc Purchase and Software License Agreement for the Open-Q 2100 (APQ8009W) Development Kit |

2.2 Reference Documents

| REFERENCE | TITLE |
|-----------|---------------------------------------|
| R-1 | Open-Q 2100 Schematics (SOM, Carrier) |
| R-2 | Open-Q 2100 BOM |

NOTE: Please contact Intrinsyc or visit <http://support.intrinsyc.com/> to get access to the reference documents.

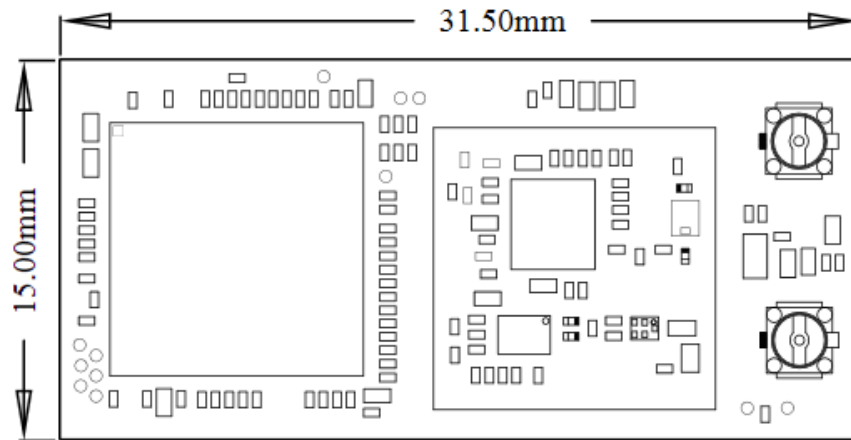
3. MECHANICAL DESIGN GUIDELINES

3.1 Introduction

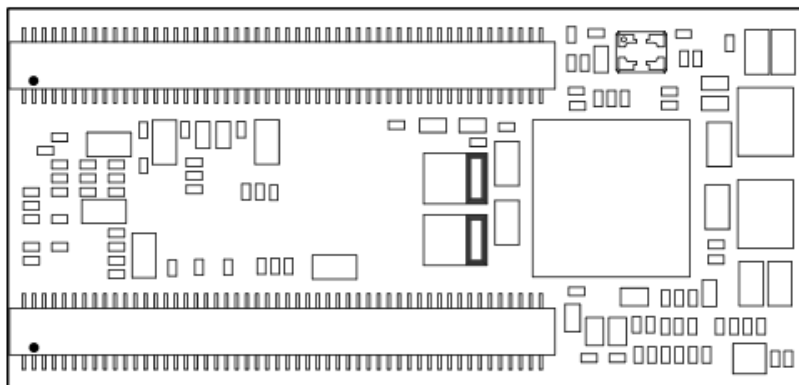
The Open-Q 2100 (APQ8009W) Development Kit provides a reference from which customers can design, develop, test, and deploy their product solutions around the popular and powerful Qualcomm APQ8009W processor. This section describes the mechanical design guidelines for developing a custom Carrier Board for the SOM.

3.2 SOM Mechanical Outline

The physical outline and dimensions of the SOM are shown in the figure below:



(a) Top view of the SOM



(b) Bottom view of the SOM

Figure 1 – SOM Mechanical Outline

3.3 Top and Bottom Height Restrictions

The tallest component on the top side and bottom side of the SOM with shield installed are 1.26mm and 1.29mm respectively.

The stacking height between Carrier Board and the SOM depends on the connector used in the Carrier board. Open-Q 2100 Carrier board uses connector with 1.5mm stacking height. It is recommended that there be no components placed in the area on the Carrier Board underneath the SOM when stacking height between the Carrier Board and SOM is 1.5mm. Please see section 3.4 below for more details.

For 3D design files, please see <http://support.intrinsyc.com/>

3.4 Carrier Board Connector, Mounting Hole and Thermal Relief Locations

The APQ8009W SOM mounts to the Open-Q carrier board through two 100-pin board to board connectors. Customers that are designing their own carrier board must ensure that their connector pinouts match the ones on the Open-Q 2100 development kit carrier board schematic (see [R-1](#))

The following mechanical features are required to connect the APQ8009W SOM to the carrier board. When designing a custom carrier board, please keep these dimensions in mind. See Figure 2 for further details.

- Board to Board connector: 100-pin, 0.4mm pitch board-board connector. The connector part number is Hirose DF40C-100DS-0.4V(51) which gives a 1.5mm stack-up distance between the carrier board and the SOM.
- Customer can choose connector with different stacking height. Please make sure the connector on the Carrier board mates with the SOM connector part number DF40C-100DP-0.4V(51).

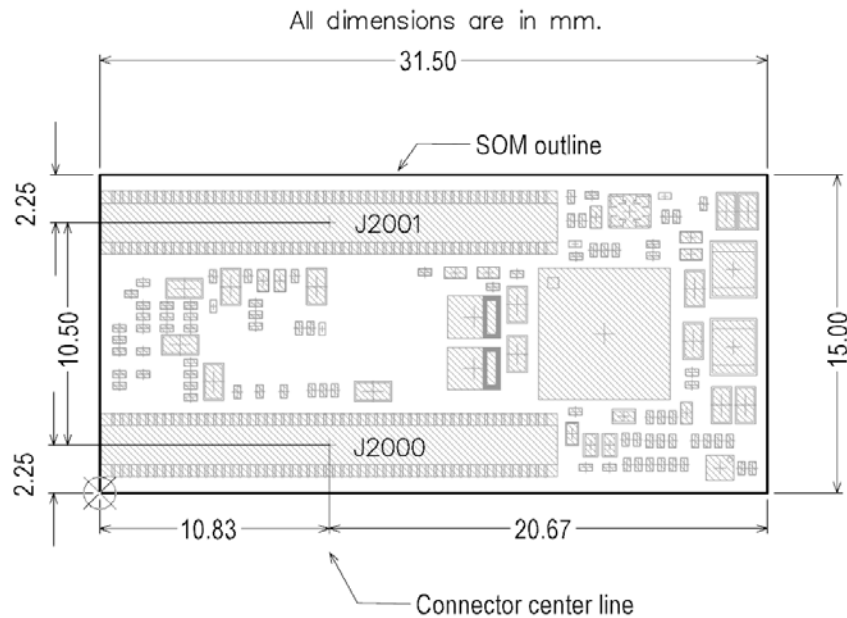


Figure 2 – SOM connectors on carrier board layout

3.5 Antenna Connectors

The SOM contains two U.FL coaxial receptacles (Hirose U.FL-R-SMT-1 (10)) for connecting to GNSS, and WLAN/ BT RF antennas (see the Open-Q 2100 bill of materials, document [R-2](#), for the mating coaxial cable part numbers).

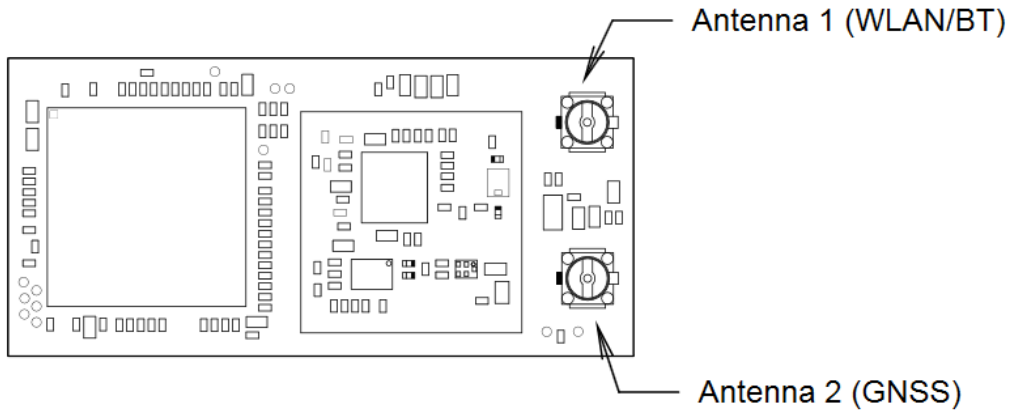


Figure 3 – Antenna connectors on the SOM

4. ELECTRICAL DESIGN GUIDELINES

4.1 Introduction

This section outlines the electrical design guidelines for developing a custom Carrier Board for the Open-Q 2100 SOM. The section below is organized by functionalities and only covers the signals that are available on the board to board connectors. Please refer to the Open-Q 2100 schematics ([R-1](#)) for more details.

If there are pinout differences between the tables below and the SOM schematic, the latter shall be assumed correct.

Please see the notes column in the sections below for any critical design guidelines.

4.2 Input Power

The APQ8009W SOM can be powered by a +3.7V DC power source or a single cell Lithium-Ion Polymer (LiPo) battery pack. See tables below for details on how to power the SOM via a power source or a battery. It is recommended that over current and reverse polarity protection circuits be implemented on the carrier board.

4.2.1 Powering SOM with DC Power Source

Table 1 – Critical Input Power Signals when Powering SOM with DC Power Source

| Board to board connector pin # | Pin Name | Description | Notes |
|--|---------------|--|---|
| J2001-75 | VCOIN | Optional +3V coin cell backup battery connection to the PM8996 PMIC. | Connect the positive terminal of the coin cell to VCOIN (J2001-75) and the negative terminal to GND. |
| J2000- [51,53,55,57,59,61,63] J2001- [62,64,66,68,70,72,74] | VPH_PWR | 3.8V DC power input to SOM. | Connect to power source input. Place the SOM input power source (3.8V) as close as possible. |
| J2000-84 | BATT_ID | Battery identification input to the PMI8916-1 PMIC on the SOM | Pull BATT_ID to GND with a 100K Ohm resistor. Add a 100K resistor population option from BATT_ID pin to the VREF_BATT_THERM (pin J2000-86). |
| J2000-88 | PM_BATT_THERM | Battery thermistor input to the PMI8916-1 PMIC on the SOM | Pull PM_BATT_THERM to GND with a 100K Ohm resistor. Add a 100K resistor population option from PM_BATT_THERM pin to the VREF_BATT_THERM (pin J2000-86). |

| Board to board connector pin # | Pin Name | Description | Notes |
|---|--------------|--|---|
| J2001-84 | OPT_1 | External charger option | Connect a 0R resistor population option to GND. Pulling OPT_1 to GND enables external charger and leaving it floating enables PMIC charger. |
| J2000-[98,100] | VDD_EAR_SPKR | Ear and class-D speaker amplifier input supply. Software configurable voltage 5V or VPH_PWR. | Expected use: Audio |
| J2000-[7,13,19,25,31,37,43,49,79,16,22,28,60,76,78] J2001-[35,61,81,85,95,38,52,60,62,82,94] | GND | Ground reference for design | |

4.2.2 Powering SOM with LiPo Battery

Table 2 – Critical Input Power Signals when Powering SOM with LiPo Battery

| Board to board connector pin # | Pin Name | Description | Notes |
|--|---------------|---|---|
| J2000-[51,53,55,57,59,61,63] J2001-[62,64,66,68,70,72,74] | VPH_PWR | 3.7V DC power input to SOM. | Connect power rail VPH_PWR to the positive terminal of the battery pack. It is strongly recommended to use over-voltage/under-voltage protection on VPH_PWR rail. Please refer section 5 for electrical specifications. |
| J2000-84 | BATT_ID | Battery identification input to the PMI8916-1 PMIC on the SOM | Connect BATT_ID rail to the battery ID terminal of the battery pack. If battery ID function is not supported by the battery or not used, pull BATT_ID low with a 100K resistor to GND. Add a 100K resistor population option from BATT_ID pin to the VREF_BATT_THERM (pin J2000-86). |
| J2000-88 | PM_BATT_THERM | Battery thermistor input to the PMI8916-1 PMIC on the SOM | Connect PM_BATT_THERM rail to the thermal resistance terminal of the battery pack. If battery pack does not have a thermistor, connect PM_BATT_THERM to GND with a 100K Ohm resistor. Add a 100K resistor population option from PM_BATT_THERM pin to the VREF_BATT_THERM (pin J2000-86). |

| Board to board connector pin # | Pin Name | Description | Notes |
|---|------------------|--|---|
| J2001-84 | OPT_1 | External charger option | Connect a 0R resistor population option to GND. Pulling OPT_1 to GND enables external charger and leaving it floating enables PMIC charger. |
| J2000-[67,69,71,73,75,77] | USB2_VBUS | USB VBUS input | Connect USB VBUS to this pin to provide USB battery charging feature |
| J2000-65 | VBAT_SNS | VBAT sense input | Connect to the VPH_PWR rail/ battery positive terminal to sense battery voltage |
| J2000-[98,100] | VDD_EAR_S PKR | Ear and class-D speaker amplifier input supply. Software configurable voltage 5V or VPH_PWR. | Expected use: Audio |
| J2000-[7,13,19,25,31,37,43,49,79,16,22,28,60,76,78] J2001-[35,61,81,85,95,38,52,60,62,82,94] | GND | Ground reference for design | |

NOTE: Users are suggested to consider external charger option when using a battery to power the SOM. Please refer the Open-Q™ 2100 carrier board schematic for the reference design. It is also advised that a minimum three terminal battery with a pin for thermal resistance be used. Select a battery with a thermal resistance (R_{th}) of 100K at 25°C.

4.3 Boot Control Signals

To initiate the SOM boot up sequence, PHONE_ON_N and APQ_RESOUT_N need to be triggered. APQ_RESOUT_N is output reset signal from CPU and PHONE_ON_N and BOOT_CONFIG[X] signals are inputs to the CPU. Figure 4 below illustrates the power on sequence during SOM boot up. Please note that the diagram shown in Figure 4 is not drawn as a timing plot but rather as a sequencing diagram.

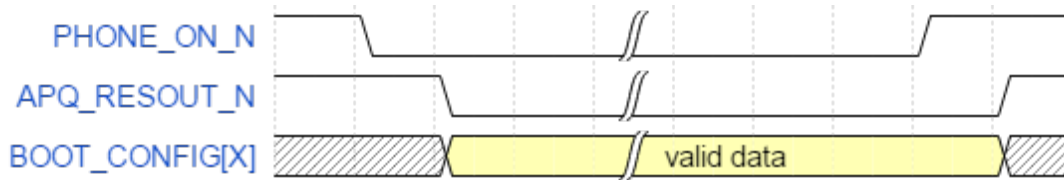


Figure 4 – Power on sequence during SOM boot up

Figure 5 shows an example of how to control the SOM boot signals. It is recommended that users follow this circuitry or implement something similar.

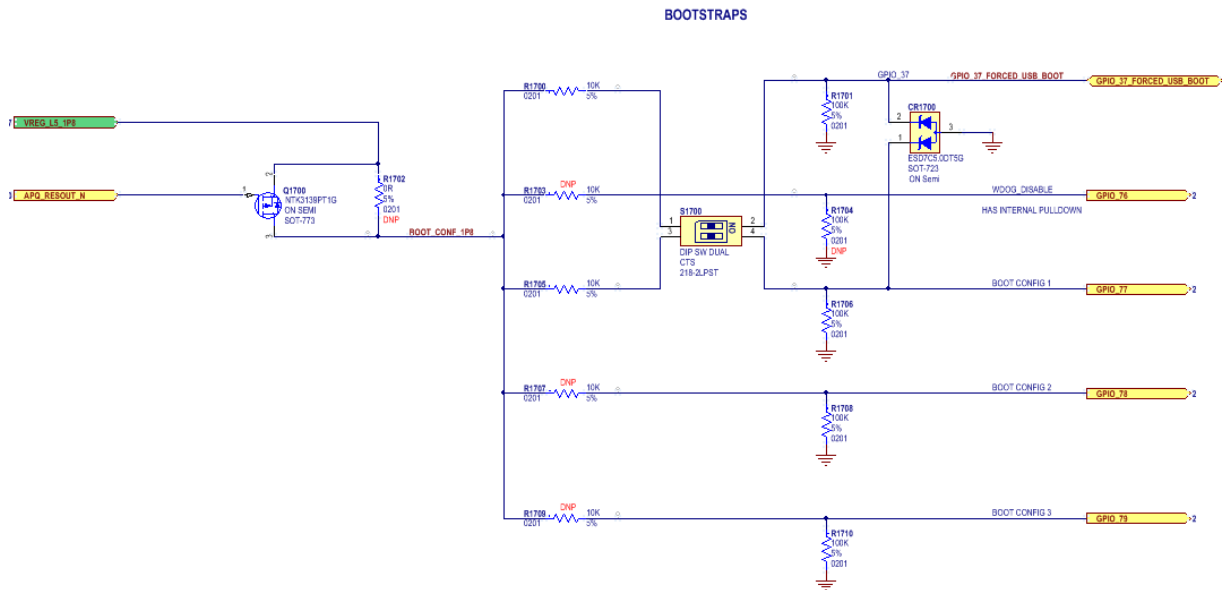


Figure 5 – Example circuitry for boot signals

The table below describes critical signals that are needed for SOM boot up.

Table 3 – Critical Boot Signals

| Board to board connector pin # | Pin Name | Description | Notes |
|--------------------------------|--------------|---|---|
| J2001-68 | PHONE_ON_N | Power on input. Internally pulled up to +1.8V on SOM. Active low. | It is recommended to use a button to control this signal. Ensure that there are NO external pulls on this line |
| J2001-72 | PMIC_RESIN_N | Reset input/Volume down. Internally pulled up to +1.8V on SOM. Active low | Connected to RESIN_N on PM8916-1. It is recommended to use a button to control this signal. Ensure that there are NO external pulls on this line |
| J2001-40 | APQ_RESOUT_N | CPU reset output | APQ_RESOUT_N asserts low upon receiving power on input from PHONE_ON_N. Ensure that there are NO external pulls on this line |
| J2000-58 | GPIO_76 | Boot configuration 0/ watchdog disable. Configures external boot device | BOOT_CONFIG[0]/WD OG_DISABLE needs to be pulled low to enable boot options. It has internal pulldown and does not require external pulldown resistor. |

| Board to board connector pin # | Pin Name | Description | Notes |
|--------------------------------|-------------------------------|---|--|
| J2001-36 | GPIO_77 | Boot configuration 1. Configures external boot device | BOOT_CONFIG[1] needs to be pulled low with 100K ohm resistor (see table below) |
| J2001-34 | GPIO_78 | Boot configuration 2. Configures external boot device | BOOT_CONFIG[2] needs to be pulled low with 100K ohm resistor (see table below) |
| J2001-55 | GPIO_79 | Boot configuration 3. Configures external boot device | BOOT_CONFIG[3] needs to be pulled low with 100K ohm resistor (see table below) |
| J2000-47 | FORCED_USB_BOOT (APQ_GPIO_37) | Forced USB boot | FORCED_USB_BOOT can be left floating/ pulled low with 100K ohm resistor. Forced USB boot for Intrinsic internal use only |

Table 4 – Boot Configurations

| Boot Options/ Sequence | GPIO_79 BOOT_CONFIG[3] | GPIO_78 BOOT_CONFIG[2] | GPIO_77 BOOT_CONFIG[1] | GPIO_37 FORCED_USB |
|-----------------------------------|--|--|--|--|
| eMMC@SDC1 → HS USB ^[1] | Pull low to GND | Pull low to GND | Pull low to GND | Pull low to GND |
| uSD@SDC2 → eMMC@SDC1 | Pull low to GND | Pull low to GND | Pull high to 1.8V during boot sequence | Pull low to GND |
| eMMC@SDC1 ^[2] | Pull low to GND | Pull high to 1.8V during boot sequence | Pull low to GND | Pull low to GND |
| HS_USB ^[3] | Pull low to GND | Pull high to 1.8V during boot sequence | Pull high to 1.8V during boot sequence | Pull low to GND |
| NAND EBI2 ^[4] | Pull high to 1.8V during boot sequence | Pull low to GND | Pull low to GND | Pull low to GND |
| FORCED USB BOOT ^[5] | Don't care | Don't care | Don't care | Pull high to 1.8V during boot sequence |

[1] Default Boot option

[2][3][4] Optional boot configurations These boot configurations are not currently supported.

[5] This option is for Intrinsic Software internal use only.

4.4 Power Output

There are several power output rails exposed on the SOM, as shown in the table below. The current capacity for each power rail is as rated from the PMIC.

Table 5 – Power Output Rails

| Board to board connector pin # | Pin Name | Description ^[a] | Notes ^[b] |
|--------------------------------|--------------|--|------------------------|
| J2000-10 | VREG_L12_SDC | LDO linear regulator L12 (50mA). Default voltage = 2.95V | Expected use: μSD card |

| Board to board connector pin # | Pin Name | Description ^[a] | Notes ^[b] |
|--|------------------------|--|--|
| J2000-80 | VREG_L6_1P8 | LDO linear regulator L6 (150mA). Default voltage = 1.8V | Expected use: Camera, display and transducer 1.8V rails |
| J2001-[77,79]^[1] | VREG_L1_1P0 | LDO linear regulator L1 (250mA). Default voltage = 1.0V | |
| J2001-[89,91] | VREG_L17_2P85 | LDO linear regulator L17 (450mA). Default voltage = 2.85V | Expected use: Display, transducers and camera 2.85V rails |
| J2001-93 | VREG_L6_1P8 | LDO voltage switch L6 (150mA). Default voltage = 1.8V | Expected use: Camera, display and transducer 1.8V rails |
| J2001-[97,99]^[2] | VREG_L9_3P3 | LDO voltage switch L9 (600mA). Default voltage = 3.3V | |
| J2001-[2,4] | VREG_L8_2P9 | LDO linear regulator L8 (400mA). Default voltage = 2.9V | Expected use: eMMC/ NAND core. SOM uses this rail to for eMMC core |
| J2001-66 | VREG_L5_1P8 | LDO linear regulator L5 (200mA). Default voltage = 1.8V | Expected use: Codec and memory 1.8V rails, WLAN IO (SOM uses this rail for WLAN IO) |
| J2001-80 | VREG_L18_2P7 | LDO linear regulator L18 (150mA). Default voltage = 2.7V | Expected use: Qualcomm RF360 (SOM uses this rail for GNSS antenna bias) |
| J2001-[96,98] | VREG_L11_SDC | LDO linear regulator L11 (800mA ^[3]). Default voltage = 2.95V | Expected use: SD/ MMC card |

[1][2] This power rail is no longer supported on the SOM
 [3] LDO L11 would be able to provide current of 800 mA to support SDR104 mode. The regulation specification of 3% would not be met. Since minimum voltage needed at SD card is only 2.7 V, the accuracy of 8.4% will be sufficient. The LDO L11 can provide current of 600 mA meeting all regulation specification.
 [a] Rated current of the LDOs will be less than the specification due to the wire bond package of the PM8916-1.
 [b] Some of the power rails are used within SOM itself.

4.5 SDIO Interface Signals

The SDC2 bus is routed out of the SOM via the board-to-board connectors on the bottom of the SOM. This bus is referenced to VREG_L11_SDC, which defaults to 2.95V. Those SDIO interface signals are listed in the table below.

Table 6 – SDIO Interface Signals

| Board to board connector pin # | Pin Name | Description | Notes |
|--------------------------------|------------------|---|------------------------------|
| J2000-1 | SDC2_CLK | SDC2 clock signal. Option to pull high to VREG_L12_SDC via 51K resistor in the Open-Q carrier board. | Used by μSD socket on Open-Q |
| J2000-[3,5,6,4] | SDC2_DATA_[0..3] | SDC2, 4-bit data bus. Option to pull high to VREG_L12_SDC via 51K resistor in the Open-Q carrier board. | Used by μSD socket on Open-Q |
| J2000-2 | SDC2_CMD | SDC2 CMD signal. Option to pull high to VREG_L12_SDC via 51K resistor in the Open-Q carrier board. | Used by μSD socket on Open-Q |

| Board to board connector pin # | Pin Name | Description | Notes |
|--------------------------------|---------------|--|--|
| J2000-8 | SD_CARD_DET_N | SD card detect signal. Pulled high to VREG_L5_1P8 via 1M resistor in the Open-Q carrier board. | Carrier board μSD socket should pull line low when card inserted |

4.6 I2C Busses

The table below shows the I2C busses that are available on the SOM. There may be other I2C signals available on other GPIO as alternate functions. Please see the APQ8009W device specification for a full listing of GPIO alternate functions. Note that CCI cannot be used as generic I2C lines. These signals are specifically dedicated for camera operations.

Table 7 – I2C Busses

| Board to board connector pin # | Pin Name | Description | Notes |
|--------------------------------|-----------------------------|--|---|
| J2000-12 | BLSP5_1_TS_I2C_SDA | CPU GPIO18. Requires 2.2K resistor pull-up to VREG_L6_1P8 on the carrier board. | Expected use: Touch screen (Display) |
| J2000-14 | BLSP5_0_TS_I2C_SCL | CPU GPIO19. Requires 2.2K resistor pull-up to VREG_L6_1P8 on the carrier board. | |
| J2000-40 | CCI_I2C_SCL | CPU GPIO30. Requires 2.2K resistor pull-up to VREG_L6_1P8 on the carrier board. | Expected use: Camera (CSI0). |
| J2000-42 | CCI_I2C_SDA | CPU GPIO29. Requires 2.2K resistor pull-up to VREG_L6_1P8 on the carrier board. | |
| J2000-48 | BLSP1_1_SENSOR_I2C_SDA | CPU GPIO6. Requires 2.2K resistor pull-up to VREG_L6_1P8 on the carrier board. | Expected use: Sensors |
| J2000-50 | BLSP1_0_SENSOR_I2C_SCL | CPU GPIO7. Requires 2.2K resistor pull-up to VREG_L6_1P8 on the carrier board. | |
| J2001-10 | BLSP4_0_SMB_I2C_SCL | CPU GPIO15. Requires 2.2K resistor pull-up to VREG_L5_1P8 on the carrier board. | Expected use: SMB charger/ Fuel gauge |
| J2001-12 | BLSP4_1_SMB_I2C_SDA | CPU GPIO14. Requires 2.2K resistor pull-up to VREG_L5_1P8 on the carrier board. | |
| J2001-26 | GPIO_112_BLSP2_BIT0_WCD_SCL | CPU GPIO112. Requires 2.2K resistor pull-up to VREG_L5_1P8 on the carrier board. | Expected use: NFC/ Connectivity connector |
| J2001-28 | GPIO_111_BLSP2_BIT1_WCD_SDA | CPU GPIO111. Requires 2.2K resistor pull-up to VREG_L5_1P8 on the carrier board. | |

4.7 BLSP Signals

The table below shows BLSP signals that are available on the SOM.

Table 8 – BLSP Signals

| BLSP # | Bit | CPU GPIO # | BLSP assignment ^[a] | | | Non-BLSP use options ^[a] | B2B pin # | Pin name |
|--------|-----|------------|--------------------------------|-----------|------------|--|-----------|--------------------------------|
| | | | SPI | UART | I2C | | | |
| 1 | 3 | 4 | MOSI | TX | - | BLSP3 SPI CS3, DMIC0_CLK, General purpose | J2000-46 | BLSP1_3_UART_TX ^[1] |
| | 2 | 5 | MISO | RX | - | BLSP2 SPI CS3, DMIC0_DATA, General purpose | J2000-44 | BLSP1_2_UART_RX ^[2] |
| | 1 | 6 | CS_N | CTS_N | SDA | General propose | J2000-48 | BLSP1_1_SENSOR_I2C_SDA |
| | 0 | 7 | CLK | RFR_N | SCL | General propose | J2000-50 | BLSP1_0_SENSOR_I2C_SCL |
| 2 | 3 | 20 | MOSI | TX | - | General Purpose | J2001-22 | BLSP2_3 |
| | 2 | 21 | MISO | RX | - | General Purpose | J2001-24 | BLSP2_2 |
| | 1 | 111 | CS_N | CTS_N | SDA | General Purpose | J2001-28 | GPIO_111_BLSP2_BIT1_WC D_SDA |
| | 0 | 112 | CLK | RFR_N | SCL | General Purpose | J2001-26 | GPIO_112_BLSP2_BIT0_WC D_SCL |
| 3 | 3 | 29 | MOSI | - | SDA | General Purpose | J2001-15 | BLSP3_3_SENSOR_SPI_MOS I |
| | 2 | 30 | MISO | - | SCL | General Purpose | J2001-19 | BLSP3_2_SENSOR_SPI_MIS O |
| | 1 | 2 | CS_N | - | - | General Purpose | J2001-17 | BLSP3_1_SENSOR_SPI_CS0_N |
| | 0 | 3 | CLK | - | - | General Purpose | J2001-21 | BLSP3_0_SENSOR_SPI_CLK |
| 4 | 3 | 12 | MOSI | - | - | General Purpose | J2001-8 | BLSP4_3_TS_RESOUT_N |
| | 2 | 13 | MISO | - | - | General Purpose | J2001-6 | BLSP4_2_TS_INT_N |
| | 1 | 14 | CS_N | - | SDA | General Purpose | J2001-12 | BLSP4_1_SMB_I2C_SDA |
| | 0 | 15 | CLK | - | SCL | General Purpose | J2001-10 | BLSP4_0_SMB_I2C_SCL |
| 5 | 3 | 16 | MOSI | - | - | General Purpose | - | - |
| | 2 | 17 | MISO | - | - | BLSP2 SPI CS2, General Purpose | - | - |
| | 1 | 18 | CS_N | - | SDA | General Purpose | J2000-12 | BLSP5_1_TS_I2C_SDA |
| | 0 | 19 | CLK | - | SCL | General Purpose | J2000-14 | BLSP5_0_TS_I2C_SCL |

[1][2] The BLSP1 bit 3 and 2 are used for debugging (UART) signals.
 [a] SOM software default configuration assignments are in bold text.

4.8 GPIO Signals

The table below shows the GPIO signals that are available on the SOM. Please see the APQ8009W and PM8916-1 device specification documents for a full listing of GPIO alternate functions.

Table 9 – GPIO Signals

| B2B connector Pin # | Pin Name^[1] | CPU GPIO # | Notes |
|----------------------------|-------------------------------|-------------------|--------------|
| J2000-12 | BLSP5_1_TS_I2C_SDA | 18 | |
| J2000-14 | BLSP5_0_TS_I2C_SCL | 19 | |
| J2000-30 | GPIO_35_CAM0_RESET_N | 35 | |
| J2000-32 | GPIO_34_CAM0_STANDBY_N | 34 | |
| J2000-34 | GPIO_32_FLASH_NOW | 32 | |
| J2000-36 | GPIO_31_FLASH_EN | 31 | |
| J2000-38 | GPIO_33_DSI2HDMI_INT_N | 33 | |
| J2000-40 | CCI_I2C_SCL | 30 | |
| J2000-42 | CCI_I2C_SDA | 29 | |
| J2000-44 | BLSP1_2_UART_RX | 5 | |
| J2000-45 | GPIO_28_DISPLAY_GP1 | 28 | |
| J2000-46 | BLSP1_3_UART_TX | 4 | |
| J2000-47 | FORCED_USB_BOOT | 37 | |
| J2000-48 | BLSP1_1_SENSOR_I2C_SDA | 6 | |
| J2000-50 | BLSP1_0_SENSOR_I2C_SCL | 7 | |
| J2000-52 | GPIO_90_KPSNS0 | 90 | |
| J2000-54 | USB_HUB_RESET_N | 74 | |
| J2000-56 | GPIO_73_WSA_EN2 | 73 | |
| J2000-58 | GPIO_76 | 76 | |
| J2000-8 | SD_CARD_DET_N | 38 | |
| J2001-1 | GPIO_98_BLSP2_SPI_CS1 | 98 | |
| J2001-10 | BLSP4_0_SMB_I2C_SCL | 15 | |
| J2001-11 | GPIO_94_ALSPG_INT_N | 94 | |
| J2001-12 | BLSP4_1_SMB_I2C_SDA | 14 | |
| J2001-13 | GPIO_97 | 97 | |
| J2001-14 | GPIO_55_TS0_GP2 | 55 | |
| J2001-15 | BLSP3_3_SENSOR_SPI_MOSI | 0 | |
| J2001-16 | GPIO_53_TS0_GP1 | 53 | |
| J2001-17 | BLSP3_1_SENSOR_SPI_CS0_N | 2 | |
| J2001-18 | GPIO_54_MAG_DRDY_INT_N | 54 | |
| J2001-19 | BLSP3_2_SENSOR_SPI_MISO | 1 | |
| J2001-21 | BLSP3_0_SENSOR_SPI_CLK | 3 | |
| J2001-22 | BLSP2_3 | 20 | |
| J2001-23 | GPIO_49_DISPLAY_GP2 | 49 | |
| J2001-24 | BLSP2_2 | 21 | |
| J2001-25 | GPIO_99_SMB_VCHG_PA_ON | 99 | |
| J2001-26 | GPIO_112_BLSP2_BIT0_WCD_SCL | 112 | |
| J2001-27 | GPIO_65_COMP_INT_N | 65 | |
| J2001-28 | GPIO_111_BLSP2_BIT1_WCD_SDA | 111 | |
| J2001-29 | GPIO_56_SMB_INOK | 56 | |
| J2001-3 | GPIO_95_WCD_INT2 | 95 | |
| J2001-30 | GPIO_58_SMB_STAT | 58 | |
| J2001-34 | GPIO_78 | 78 | |
| J2001-36 | GPIO_77 | 77 | |
| J2001-42 | GPIO_67_FG_ALARM | 67 | |
| J2001-51 | GPIO_69_USER_LED2 | 69 | |
| J2001-53 | GPIO_87 | 87 | |
| J2001-54 | GPIO_86 | 86 | |
| J2001-55 | GPIO_79 | 79 | |

| B2B connector Pin # | Pin Name ^[1] | CPU GPIO # | Notes |
|---------------------|-------------------------|----------------------------|-------|
| J2001-56 | GPIO_71 | 71 | |
| J2001-57 | GPIO_36_ACC1_INT2_N | 36 | |
| J2001-58 | GPIO_68_USER_LED1 | 68 | |
| J2001-59 | GPIO_72_WSA_EN1 | 72 | |
| J2001-6 | BLSP4_2_TS_INT_N | 13 | |
| J2001-63 | GPIO_83_GYRO_INT_N | 83 | |
| J2001-64 | GPIO_66_FG_CHARGE_EN | 66 | |
| J2001-65 | CAM_MCLK0 | 26 | |
| J2001-67 | GPIO_91_KPSNS1 | 91 | |
| J2001-69 | GPIO_92 | 92 | |
| J2001-7 | GPIO_110_DSI_SW_SEL | 110 | |
| J2001-71 | OLED_RST_N | 25 | |
| J2001-73 | OLED_TE | 24 | |
| J2001-8 | BLSP4_3_TS_RESOUT_N | 12 | |
| J2001-83 | GPIO_70 | 70 | |
| J2001-87 | GPIO_84 | 84 | |
| J2001-9 | GPIO_96_ACC1_INT1_N | 96 | |
| | | PMIC GPIO/MPP # | |
| J2001-78 | PMIC_GPIO_2 | PMIC GPIO 2 | |
| J2001-90 | PMIC_MPP_2 | PMIC MPP 2 | |
| J2001-92 | PMIC_MPP_3 | PMIC MPP 3 | |
| J2001-88 | WCD_ELDO_EN_PMGPIO4 | PMIC GPIO 4 | |
| J2001-74 | WLED_PWM_MPP_4 | PMIC MPP 4 | |

[1] GPIO pins can support multiple functions. To assign GPIOs to particular functions, designers must identify all their application's requirements and map each GPIO to its function- carefully avoiding conflicts in GPIO assignments.

4.9 Audio Input/ Output Interface

The signals contained in this section are used for audio outputs or inputs. All signals originate or travel to the PMIC (PM8916-1) audio codec on the SOM unless specified. Please refer to the PM8916-1 device specifications for more detail.

Table 10 – PMIC Audio Interface Signals

| Board to Board Pin # | Pin Name | Description | Notes |
|----------------------|----------------|--|--|
| J2000-98 | VDD_EAR_SPKR | Earphone and class-D speaker amplifier input supply. | Software configurable voltage 5V or VPH_PWR. |
| J2000-81 | SPKR_OUT_P | Class-D loudspeaker + output | |
| J2000-83 | SPKR_OUT_N | Class-D loudspeaker - output | |
| J2000-90 | CDC_MIC_BIAS2 | Analog mic-2 bias output ^[1] | |
| J2000-92 | CDC_MIC_BIAS1 | Analog mic-1 bias output ^[2] | |
| J2000-91 | CDC_MIC3_P | Analog mic-3 input (second mic) | |
| J2000-89 | CDC_MIC1_P | Analog mic-1 input (main mic) | |
| J2000-85 | CDC_HS_DET | Headset detection input | |
| J2000-97 | CDC_HPH_REF | Headphone GND sensing | |
| J2000-95 | CDC_HPH_R | Headphone Right Audio Signal | |
| J2000-99 | CDC_HPH_L | Headphone Left Audio Signal | |
| J2000-93 | CDC_HDS_MIC2_P | Analog mic-2 input (headset mic) | |

| Board to Board Pin # | Pin Name | Description | Notes |
|----------------------|---------------|--------------------------------|-------|
| J2000-94 | CDC_GND_CFILT | Ground reference for PMIC bias | |
| J2001-100 | FM_HEADSET | FM antenna connection | |

[1][2] Microphone bias voltage 1.6V ~ 2.85V at 3mA microphone load

4.9.1 Analog Microphone Inputs

Qualcomm’s PMIC8916-1 audio supports three single ended microphone inputs. The Figure 6 below shows an example of an analog ECM type microphone connected to the PMIC mic input. Note that external 2.2K pull-up resistor is optional and it is recommended to use internal MIC_BIAS 2.2K pull-up (not shown in the figure). It is not recommended to use an external capacitor on the MIC_BIAS line with ECM-type microphone inputs. When using MEMS-type of the microphone, it is recommended to use MIC_BIAS with external 0.1uF capacitors as shown in Figure 7. Any filter capacitors and protection diodes should be placed close to the off-board connector or microphone lines.

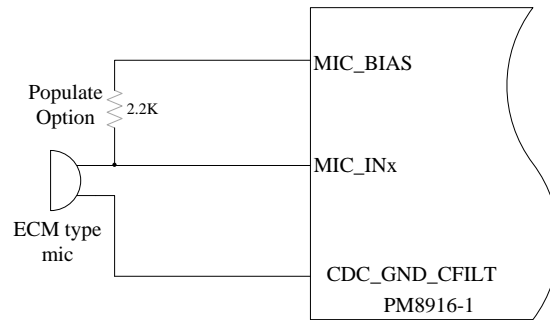


Figure 6 – Analog microphone (ECM type) connected in a single ended configuration

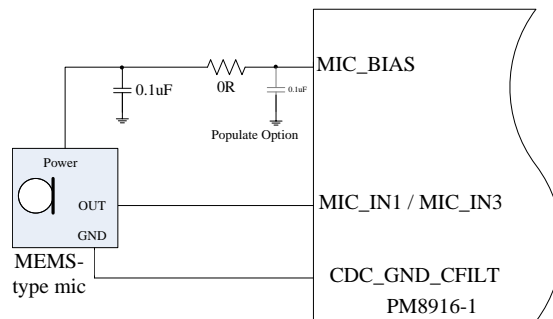


Figure 7 – Analog microphone (MEMS type) connected in a single-ended configuration

4.10 LED Signals

The table below shows the LED signals that are available on the SOM.

Table 11 – LED Signals

| B2B connector pin # | Pin Name | Description | Notes |
|---------------------|----------------|---|---|
| J2000-82 | CHG_LED_SINK | PM8916-1 charging indication LED driver output (5mA sink current rated) | This pin cannot be used to drive LED if linear battery charging is not used (OPT_1 is grounded) |
| J2001-90 | PMIC_MPP_2 | PM8916-1 Home row LED drive (40mA sink current per MPP) | |
| J2001-74 | WLED_PWM_MPP_4 | PMI8996-1 WLED PWM LED output | |

4.11 MIPI Display Interface (DSI)

The signals shown in the table below, describe those used for the MIPI display interface that is available on the SOM. When connecting to MIPI differential pair signals, the designer should be aware of the impedance and trace length matching requirements that are necessary for these high-speed signals. Please reference the MIPI standard for additional details.

Table 12 – MIPI Display Interface Group

| B2B connector pin # | Pin Name | Description | Notes |
|---------------------|---------------------|--------------------------------------|-------|
| J2000-[18,20] | MIPI_DSI0_CLK_N/P | MIPI DSI clock differential pair | |
| J2000-[21,23] | MIPI_DSI0_LANE0_P/N | MIPI DSI data lane differential pair | |
| J2000-[24,26] | MIPI_DSI0_LANE1_N/P | MIPI DSI data lane differential pair | |
| J2000-[15,17] | MIPI_DSI0_LANE2_P/N | MIPI DSI data lane differential pair | |
| J2000-[9,11] | MIPI_DSI0_LANE3_P/N | MIPI DSI data lane differential pair | |
| J2000-47 | FORCED_USB_BOOT | Backlight Enable | |
| J2001-71 | OLED_RST_N | DSI display reset | |

4.12 MIPI Camera Interface (CSI)

The signals shown in the table below, describe those used for the MIPI camera interface that is available on the SOM. When connecting to MIPI differential pair signals, the designer should be aware of the impedance and trace length matching requirements that are necessary for these high-speed signals. Please reference the MIPI standard for additional details.

Table 13 – MIPI Camera Interface Group

| B2B connector pin # | Pin Name | Description | Notes |
|---------------------|------------------------|--------------------------------------|-------|
| J2000-[33,35] | MIPI_CSI0_CLK_N/P | MIPI CSI clock differential pair | |
| J2000-[39,41] | MIPI_CSI0_LANE0_N/P | MIPI CSI data lane differential pair | |
| J2000-[27,29] | MIPI_CSI0_LANE1_P/N | MIPI CSI data lane differential pair | |
| J2001-65 | GPIO_26_CAM_MCLK0 | Camera master clock 0 | |
| J2000-36 | GPIO_31_FLASH_EN | Camera control interface timer 0 | |
| J2000-30 | GPIO_35_CAM0_RESET_N | Camera reset | |
| J2000-32 | GPIO_34_CAM0_STANDBY_N | Camera standby | |
| J2000-34 | GPIO_32_FLASH_NOW | Camera control interface timer 1 | |

4.13 USB Interface Signals

The table below shows the USB 2.0 signals that are available on the SOM. When connecting to USB differential pair signals, the designer should be aware of the impedance and trace length matching requirements that are necessary for these high-speed signals. Please reference the USB 2.0 standard for additional details.

Table 14 – USB Interface Signals

| B2B Conn Pin # | Pin Name | Description | Notes |
|---------------------------|---------------|---------------------------------------|-------|
| J2001-[31,33] | USB2_HS_D_N/P | USB port high-speed differential pair | |
| J2000-[67,69,71,73,75,77] | USB2_VBUS | PM8916-1 USB charger input source. | |
| J2001-32 | USB2_HS_ID | USB port ID signal | |

4.14 RF Antenna Connections

The Open-Q™ 2100 SOM has single band WCN3620 Wi-Fi/BT chipset and WGR7640 GNSS receiver. The SOM contains two U.FL coaxial receptacles (Hirose U.FL-R-SMT-1 (10)) for connecting to GNSS, and WLAN/ BT RF antennas as shown in the figure below. Please refer corresponding datasheet for detailed specifications.

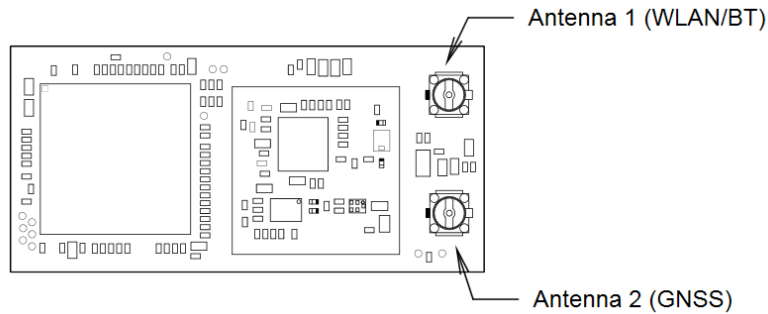


Figure 8 – Physical location of Antenna 1 and Antenna 2 on SOM

Table 15 – RF Signals via U.FL Coaxial Receptacles

| Antenna | Description | Notes |
|-----------|--|--|
| Antenna 1 | RF signal interface with Qualcomm WCN3620 Wi-Fi/BT chipset | Antenna1 is for WLAN/BT. Use a single band (2.4 GHz) antenna |
| Antenna 2 | RF signal interface with Qualcomm WGR7640 | Connect to external GNSS antenna via coax cable. The SOM provides a 2.7V output on the U.FL connector. Therefore, it is recommended that an active GNSS antenna is used. |

4.15 Miscellaneous Signals

The table below shows some miscellaneous signals that are available on the SOM via board to board connectors. These signals support different functionalities on the SOM. Please refer to their designated data sheets for more details regarding how these signals are used.

Table 16 – Miscellaneous Signals

| B2B Conn Pin # | Pin Name | Description | Notes |
|----------------|--------------|---|--|
| J2001-76 | BBCLK2 | Baseband(low power) 19.2MHz XO output 2 | |
| J2001-84 | OPT_1 | Option hardware configuration control bit 1 | See Table 17 for valid configuration options. |
| J2001-86 | OPT_2 | Option hardware configuration control bit 1 | |
| J2001-5 | PON_RESET_N | Power-on reset output control connected to CPU | Please place a 10nF/10V capacitor close to the SOM. |
| J2001-40 | APQ_RESOUT_N | CPU reset output | See section 4.3 for usage. |
| J2001-68 | PHONE_ON_N | Keypad power-on detect input | |
| J2001-70 | CBLPWR_N | Cable power-on detect input | Internal pull-up to VDD. Initiates power-on when grounded. |
| J2001-72 | PMIC_RESIN_N | Active low reset input. Also, serves as a volume down (-) button. | |

Table 17 – Hardware option configurations

| B2B Conn Pin # | Pin Name | Pin logic | Description |
|----------------|----------|-----------|--|
| J2001-84 | OPT_1 | Hi-Z | Internal charger is used |
| | | GND | External charger is used |
| J2001-86 | OPT_2 | Hi-Z | No vibrator operation during pre-power-on |
| | | GND | One-time vibration for 100ms during pre-power-on |

5. ELECTRICAL SPECIFICATIONS

5.1 Absolute Maximum Ratings

The input power to the SOM is provided by a power supply (battery or wall adapter) and also a USB source, for battery charging purposes. All input power sources enter the PM8916-1, which then distributes power via LDOs and switching power supplies. Since these input sources are susceptible to external factors, the table below shows the absolute maximum ratings in which PM8916-1 can be exposed to without experiencing functional failure.

Table 18 – Absolute Maximum Input Power Ratings

| Parameter | Min | Max | Units |
|--|------|-----|-------|
| Battery or DC power input (VPH_PWR / VBAT_SNS) | -0.5 | +6 | V |
| 5V USB VBUS battery charger input voltage source (USB2_VBUS) | -0.5 | +16 | V |
| Earphone and class-D speaker amplifier supply (VDD_EAR_SPKR) | -0.5 | +6 | V |

5.2 Operating Conditions

According to component datasheet values, the operating conditions outline the parameters in which a user can control the behavior of the SOM. If used within the following conditions as outlined in Table 19 and Table 20 below, the SOM will meet all performance specifications listed in section 7, unless otherwise noted (provided the absolute maximum ratings have never been exceeded).

Table 19 – Operating power input conditions

| Parameter | Min | Typ. | Max | Units |
|--|---------|---------|------|-------|
| Battery or DC power input (VPH_PWR) | +3.5 | +3.7 | +4.2 | V |
| 5V USB VBUS battery charger input voltage source (USB2_VBUS) | +3.7 | +5 | +9 | V |
| Earphone and class-D speaker amplifier supply (VDD_EAR_SPKR) | VPH_PWR | VPH_PWR | +5 | V |

The DC electrical characteristics for the SOM voltage output rails are listed in section 4.5 above.

5.3 Operating Temperature

The SOM operating temperature ratings listed below are based only on the operating temperature grade of the SOM components. Users should consider the specific environmental conditions in which the final product is used in.

Table 20 – Operating temperature conditions

| Parameter | Min | Typ. | Max | Units |
|-------------|-----|------|-----|-------|
| Overall SOM | -25 | +25 | +85 | °C |

Note: If the user is using SOM in extreme environmental conditions, care must be taken from exposing the Wi-Fi/ BT module from exceeding these ratings.

6. POWER CONSUMPTION

Power consumption tests have been done on the SOM under common operational modes. These results are outlined in the table below. All tests were executed at room temperature with Android 7.0 running with the Open-Q 2100 carrier board. Since measurements were taken on the VPH_PWR rail, the power consumed reflects what the SOM consumes during the given scenario.

Table 21 – Power consumptions

| Operational Modes | Description | Power |
|----------------------|--|-------|
| Suspend (Wi-Fi Off) | Power consumption when system placed in standby (Wi-Fi Off) | TBD |
| Suspend (Wi-Fi On) | Power consumption when system placed in standby (Wi-Fi On) | TBD |
| Video Record (TBD) | Power consumption when system recording TBD video | TBD |
| Video Playback (TBD) | Power consumption when system playing back TBD video | TBD |
| Audio Playback | Power consumption when system playing back MP3 ¹ | TBD |
| Wi-Fi Download | Power consumption when system downloading large file via Wi-Fi | TBD |
| Wi-Fi Upload | Power consumption when system uploading large file via Wi-Fi | TBD |
| Quad Core | Power consumption when system is running all 4 cores at 100% | TBD |
| Single core | Power consumption when system is running only 1 core at 100% (others off/ suspend) | TBD |

Note: The results above are averages of the power consumed over 30 minutes (may vary depending on test case).

¹ LCD screen has been turned off for this use case